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Adaptive control - Wikipedia

Adaptive control is a control method used in control systems to accommodate with parameters which vary. Adaptive control is basically refers to the feedback control system that does not need a priori information about the system it is to be controlled.

Adaptive Cruise Control - Wikipedia

Adaptive Cruise Control is a feature that could be activated by the owner of a car, truck, or van, depending on the vehicle's capabilities and features. It is a system that allows the driver to set a desired speed and a gap distance to the car in front of them. As a result, the control system will automatically adjust the vehicle's speed to maintain that gap distance. This technology is designed to improve traffic flow and reduce the risk of rear-end collisions.

Robust Control Theory - Carnegie Mellon University

Robust Control theory is a method to analyze the performance of a control system with changing system parameter. It provides a technique to design control systems that are insensitive to a wide range of uncertainties.

Reference Article: Nature


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